

① Finishing Online Gradient Descent

Thm: Let f_1, \dots, f_T be convex functions and
 $w_1 = 0$

$$w_{t+1} = w_t - \eta \nabla f_t(w_t)$$

for some $\eta > 0$. Suppose

$$\|\nabla f_t\| \leq G \quad \forall t.$$

Then $\forall w$

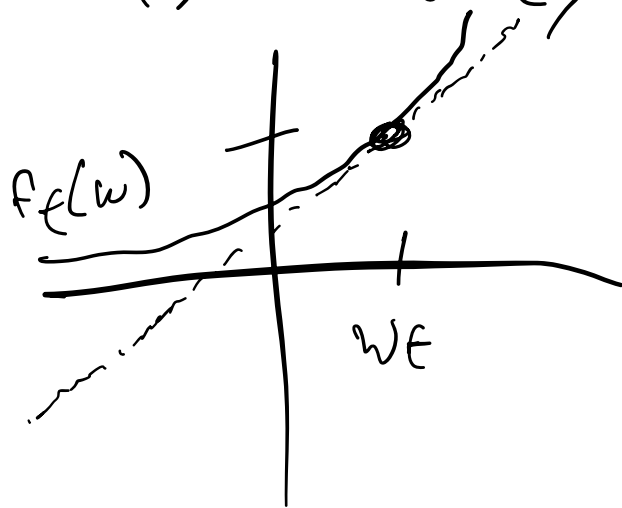
$$\sum_{t=1}^T f_t(w_t) - \sum_{t=1}^T f_t(w) \leq \eta G^2 T + \frac{\|w\|_2^2}{\eta}$$

If $\eta = \frac{1}{\sqrt{T}}$ $\longrightarrow = (G^2 + \|w\|_2^2) \sqrt{T}$

PF: Show last time when f_ϵ is
linear.

Reduction to linear!

$$\forall w \quad f_\epsilon(w_\epsilon) + \langle \nabla f_\epsilon, w - w_\epsilon \rangle \leq f_\epsilon(w)$$



$$\sum_{t=1}^T (f_t(w_t) - f_t(w)) \leq \sum_{t=1}^T \langle \nabla f_t, w_t - w \rangle$$

regret at time t
regret for

$$J_t(w) = \langle \nabla f_t(w_t), w \rangle$$

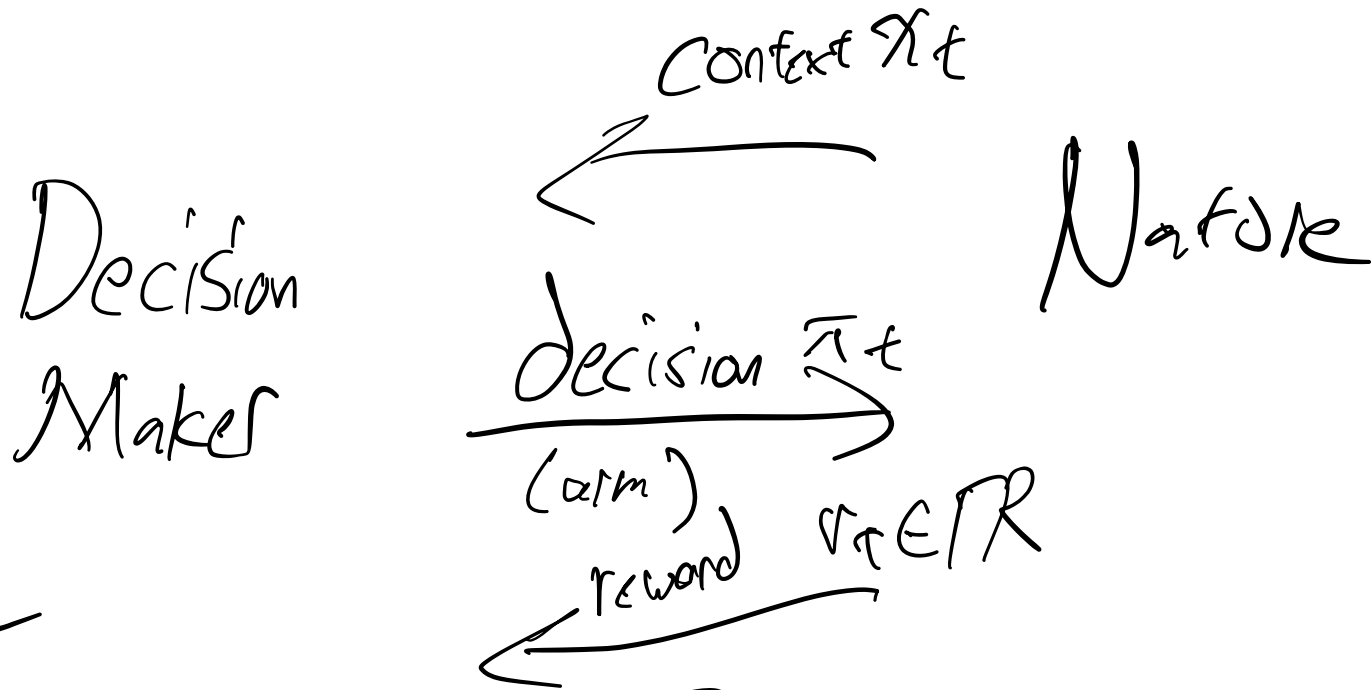
Apply OGD to the sequence

$$J_1, \dots, J_T$$

$$y_t = \langle w^*, x_t \rangle + \beta \epsilon$$

$$f_t(w) = (\langle w^*, x_t \rangle - \langle w, x_t \rangle)^2$$

Back to Contextual Bandit



Expected

$$\mathbb{E} \left[\sum_{t=1}^T r_t - \sum_{t=1}^T \max_{\pi} f^*(x_t, \pi) \right]$$

$$\pi_t \in [K]$$

of arms

Assumption:

independent
mean-zero noise

$$r_t = f^*(x_t, \pi_t) + \zeta_t$$

for some $f^* \in \mathcal{F}$

unknown

known to us.

Example (Linear Contextual Bandit) $\theta \in \mathbb{R}^d$

$$\mathcal{F} = \left\{ f(x_t, \pi_t) = \langle \theta, \phi(x_t, \pi_t) \rangle \right\}$$

$$f^*(x_t, \pi_t) = \langle \theta^*, \phi(x_t, \pi_t) \rangle$$

known feature map

$\gamma > 0$

Square CB (γ) [Foster-Rakhtin '20]

Assumes access to online regression

Oracle for \mathcal{F} (e.g. OGD for linear classes)

For $t=1$ to T :

1. Receive context x_t .

2. Use oracle \hat{f}_t to forecast $\hat{f}_t(x) = \hat{f}_t(x_t, \pi)$

Let $\hat{\pi} = \underset{\pi}{\operatorname{argmax}} \hat{f}_t(\pi)$ $\forall \pi \in [K]$

$$\sum_{\pi} p_t(\pi) = 1$$

3. $p_t(\pi) = \lambda + \gamma (\hat{f}_t(\hat{\pi}) - \hat{f}_t(\pi))$ for $\pi \in [1, K]$

4. Sample $\pi \sim p_t$ and play it, observe reward r_t
5. Update regression oracle w/ (x_t, π_t, r_t) .

Thm: